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'-----Title-----
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' File.....keyless_entry.pbp
' Started....6/20/06
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'-----Variables-----
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x          VAR    BYTE    'initialize variables
b0         VAR    BYTE
y          VAR    BYTE
door       VAR    BYTE
dist_raw   VAR    WORD
dist_inch  VAR    WORD
l          VAR    WORD
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'-----Constants/Defines-----
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conv_inch  CON    15
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'-----Main Code-----
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y = 1
l = 0
PAUSE 1500                                'initialize LCD

HIGH 5                                     'initialize bi-colored LED to red
LOW 6

FOR b0 = 1 TO 50                           'initialize servos
PULSOUT 2,210
PAUSE 20
NEXT                                       'unlock door

FOR b0 = 1 TO 85                           'close door part of the way
PULSOUT 7,175
PAUSE 20
NEXT

FOR b0 = 1 TO 20                           'close door more
PULSOUT 7,195
PAUSE 20
NEXT

FOR b0 = 1 TO 50                           'close door completely and lock it
PULSOUT 7,210
PULSOUT 2,100
PAUSE 20
NEXT

LCDOUT $FE,1,"    Locked    "            '"Locked" appears on top
                                           'line of LCD
LCDOUT $FE,$C0,"Step up to door "        '"Step up to door" appears on
                                           'bottom line of LCD
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loop:
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GOSUB sonar                                'get sonar reading

IF dist_inch < 24 THEN GOTO sensed         'if reading is < 24 then goto
sensed                                     'line of LCD
LCDOUT $FE,$C0,"Step up to door"          '"Step up to door" appears on
bottom                                    'variable "l" incremented by 1

l = l + 1
midloop:

SERIN 4,4,10,loop,[68],x                  'waits 10 miliseconds for IR signal
IF x = 1 THEN GOTO lock                    'if last byte of signal is 1
                                           'then lock
IF x = 2 THEN GOTO unlock                  'if last byte of signal is 2
                                           'then unlock

GOTO loop

sensed:
IF l < 3 THEN GOTO spot                    'this sets the sonar's sensitivity
LCDOUT $FE,$C0," *****STOP***** "     '"*****STOP*****" appears on bottom
                                           'line of LCD
PAUSE 1500                                 'display "*****STOP*****" for
                                           '1.5 seconds

spot:
LCDOUT $FE,$C0,"Unlock with FOB "         '"Unlock with FOB" appears on
bottom                                    'line of LCD

l = 0                                       'variable "l" = 0

GOTO midloop

lock:                                       'lock subroutine

IF y = 1 THEN                              'this decides if the door is
PAUSE 100                                  'already locked if door is locked
GOTO loop                                  'it won't try to lock it if door
ENDIF                                       'is unlocked it will

HIGH 5                                      'bi-colored LED is red
LOW 6

FOR b0 = 1 TO 85                            'close door part of the way
PULSOUT 7,185
PAUSE 20
NEXT

FOR b0 = 1 TO 20                            'close door more
PULSOUT 7,195
PAUSE 20
NEXT

FOR b0 = 1 TO 50                            'close door completely and lock it
PULSOUT 7,220
PULSOUT 2,100
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    PAUSE 20
    NEXT

    LCDOUT $FE,1,"    Locked    "    "'Locked" appears on top line of
LCD
    y = 1

    GOTO loop

unlock:    'unlock subroutine

    IF y = 2 THEN    'this decides if the door is
    PAUSE 100    'already unlocked if door is
unlocked
    GOTO loop    'it won't try to unlock it if door
    ENDIF    'is locked it will

    HIGH 6    'bi-colored LED is green
    LOW 5

    FOR b0 = 1 TO 50    'unlocks door
    PULSOUT 2,210
    PAUSE 20
    NEXT

    FOR b0 = 1 TO 90    'opens door part of the way
    PULSOUT 7,60
    PAUSE 20
    NEXT

    FOR b0 = 1 TO 20    'opens door completely
    PULSOUT 7,50
    PAUSE 25
    NEXT

    LCDOUT $FE,1,"    Unlocked    "    "'Unlocked" appears on top line of
LCD
    y = 2

    GOTO loop

sonar:    'sonar subroutine

    PULSOUT portb.0,1    'send 1 milisecond pulse to sonar
    PULSIN portb.1,1,dist_raw    'times the pulse width and stores
it
    dist_inch = (dist_raw/conv_inch)    'in variable dist_raw convert raw
    'data into inches
    RETURN    'go back to main program
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